

**Elevator Modernization:
An Effective Way to Improve the Performance,
Efficiency and Safety of Aged Elevators**
針對升降機老化：
提升其性能、效率和安全性

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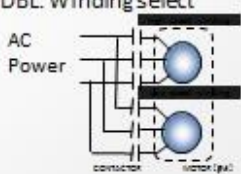

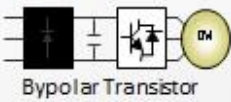
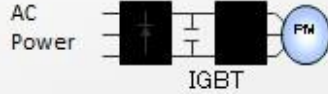
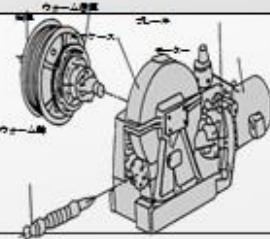
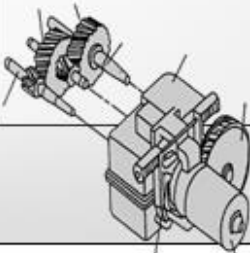

In Hong Kong,
>20,000 Elevators
being operated for over 20 years

User's Expectation



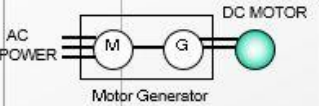
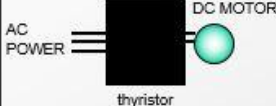





User's Expectations on Elevators:

- Riding Comfort
- Reliability
- Energy Performance/ Efficiency
- Traffic Handling Capacity
- Nowadays Safety Codes

Low Speed Elevator

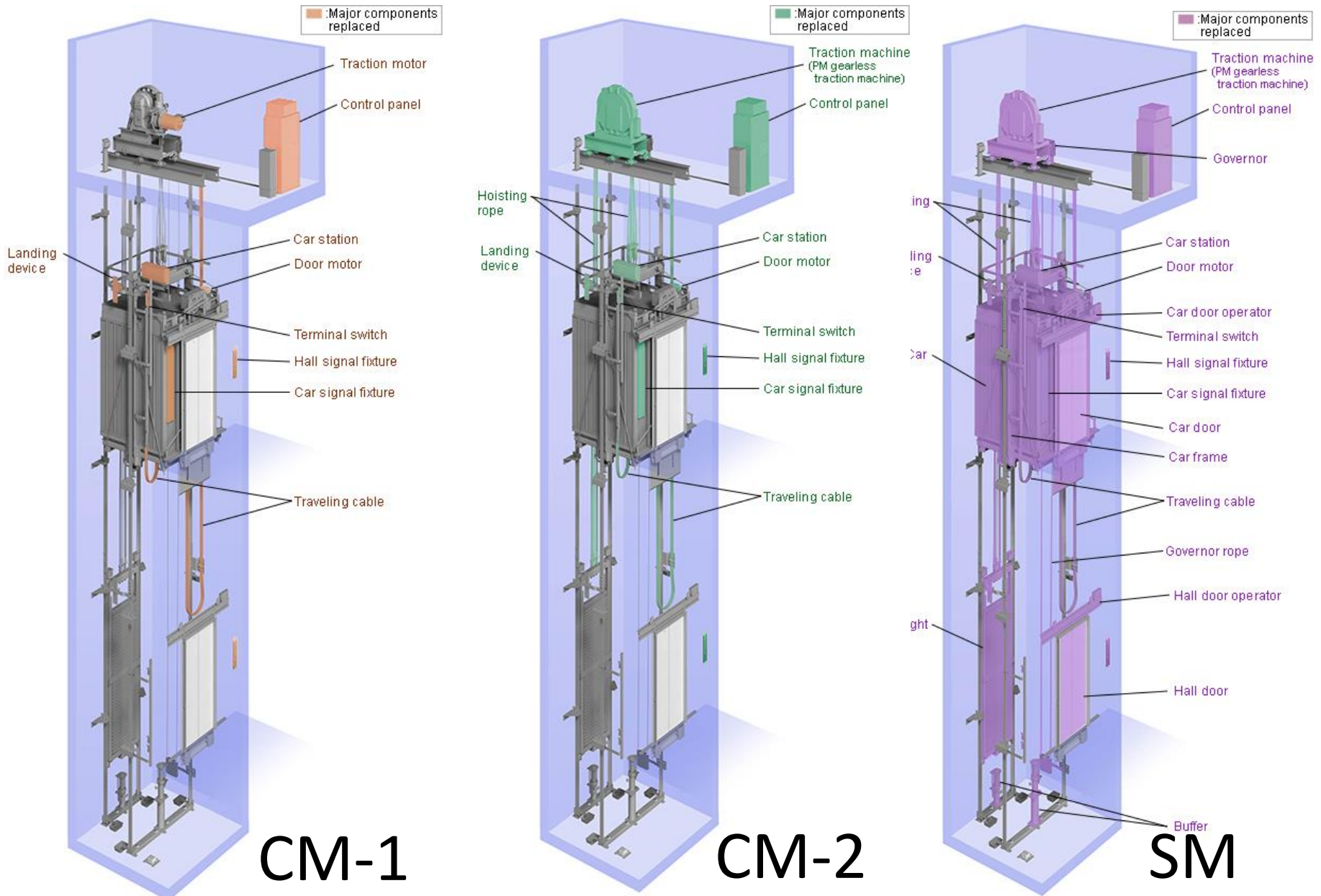
Date		1970	1980	1990	2000	2010
Control		Relay 	Micro-Processor 			
Motor Drive		DBL. Winding select AC Power 	Primary voltage control AC Power  Thyristor	Invertor Control AC Power  Bypolar Transistor	AC Power  IGBT	
Power Device		Contactor	Thyristor	Bypolar transistor	IGBT(Insulated Gate Bypolar Transistor)	
Traction Machine	Motor	Induction Motor (IM)				Synchronous Motor (PM)
	Mechanical Efficiency	Worm Gear 			Helical Gear 	Gearless 
Machine Room		With Machine Room				Machine room less

High Speed Elevator

Year		1970	1980	1990	2000	2010
Control		Relay circuit 		Microprocessor controlled 		
Motor Drive		Ward-Leonard <small>M= Induction Motor</small> <small>G= DC generator</small>  Motor Generator DC MOTOR	Thyristor Leonard  thyristor DC MOTOR	Inverter (VVVF)  Bypolar transistor IM		 IGBT PM MOTOR
Power Device		Motor Generator Set		Thyristor	Bypolar Transistor	IGBT
Traction Machine	Motor	DC MOTOR		Induction Motor		Synchronous Motor (Permanent Magnet)
	Mechanical Transmission	gearless 		Helical gear 	Gearless 	

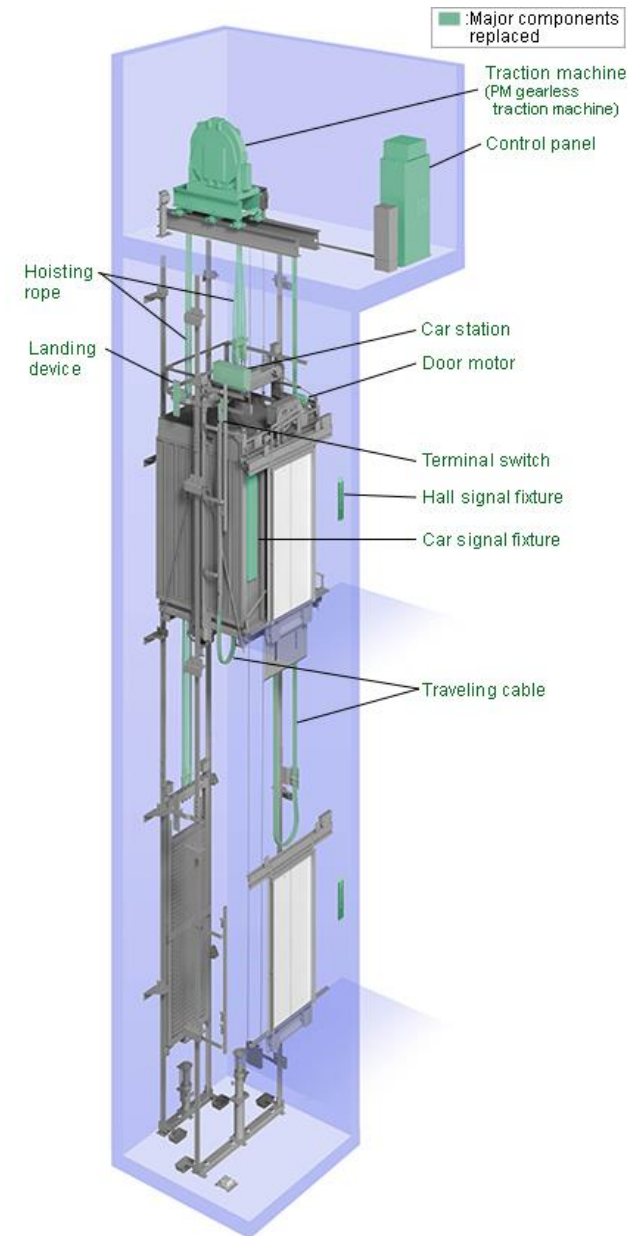
	Riding Comfort		Reliability		Energy Efficiency		Traffic Handling Capacity	
Time	70's Tech.	Current Tech.	70's Tech.	Current Tech.	70's Tech.	Current Tech.	70's Tech.	Current Tech.
Technology	AC-2	VVVF	Relay Type	Computerized Control	AC-2/ ACVV + Worm- gear + Induction Motor	VVVF + PM Gearless Motor	Relay type, non- program mable	Computeri zed, AI Logic
Characteristics	Discrete and hard	Smooth and seamless	Contact type, breakdown easily	PCB type, static, less breakdown	Induction motor saturate, mech. trans, energy loss	V/f = Constant, gearless, energy efficient	Single logic	Rule-set optimizer, real time simulation
Related Components	Motor Drive		Control Panel		Control Panel + Motor Drive + Traction Machine		Control Panel	

Modernization Scope



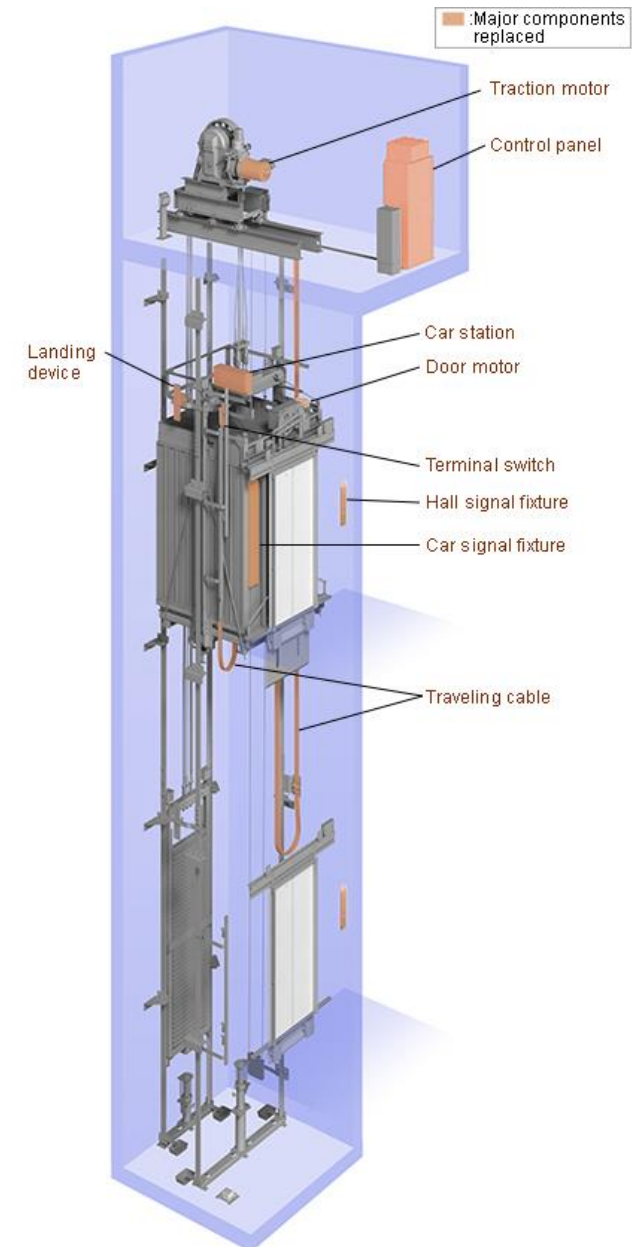
CM-2

- Traction machine
- Control panel
- Shaft signalling
- Door motor
- Travelling cable
- Indicators

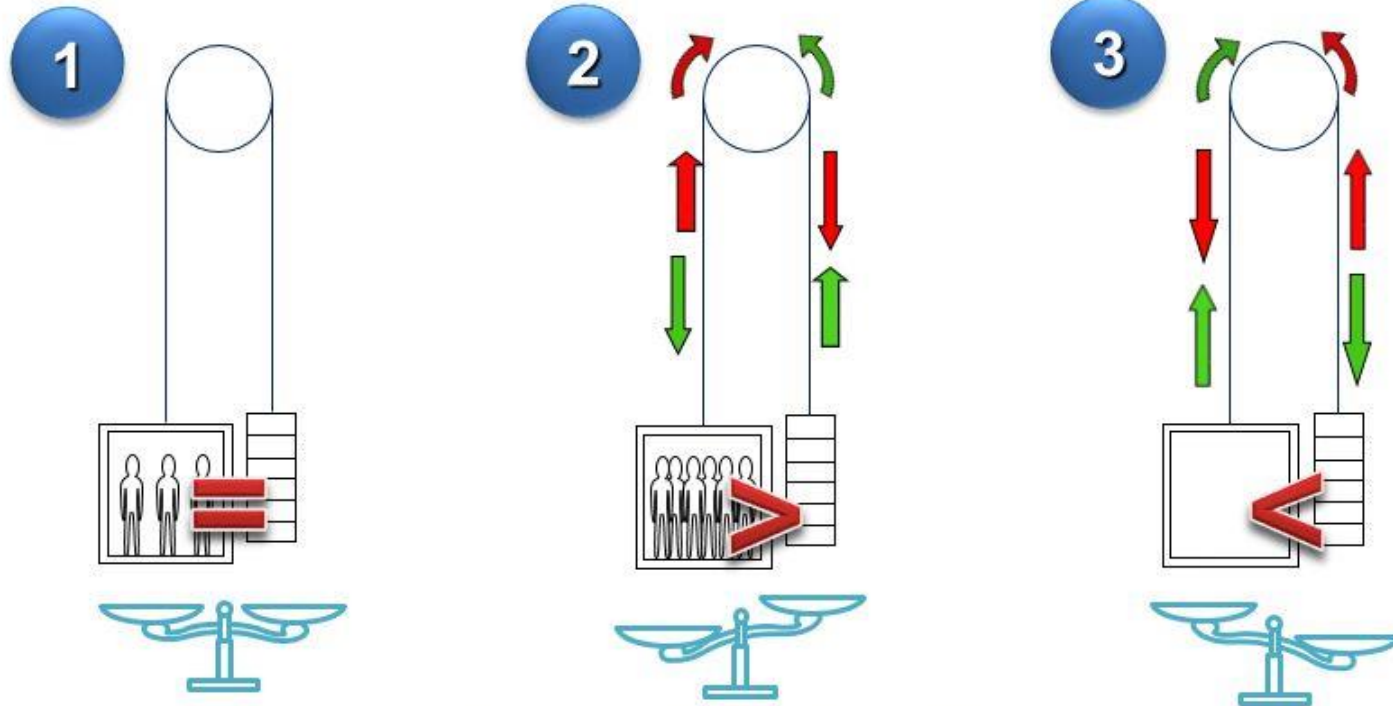


CM-1

- Traction motor
- Control panel
- Shaft signalling
- Door motor
- Travelling cable
- Indicators

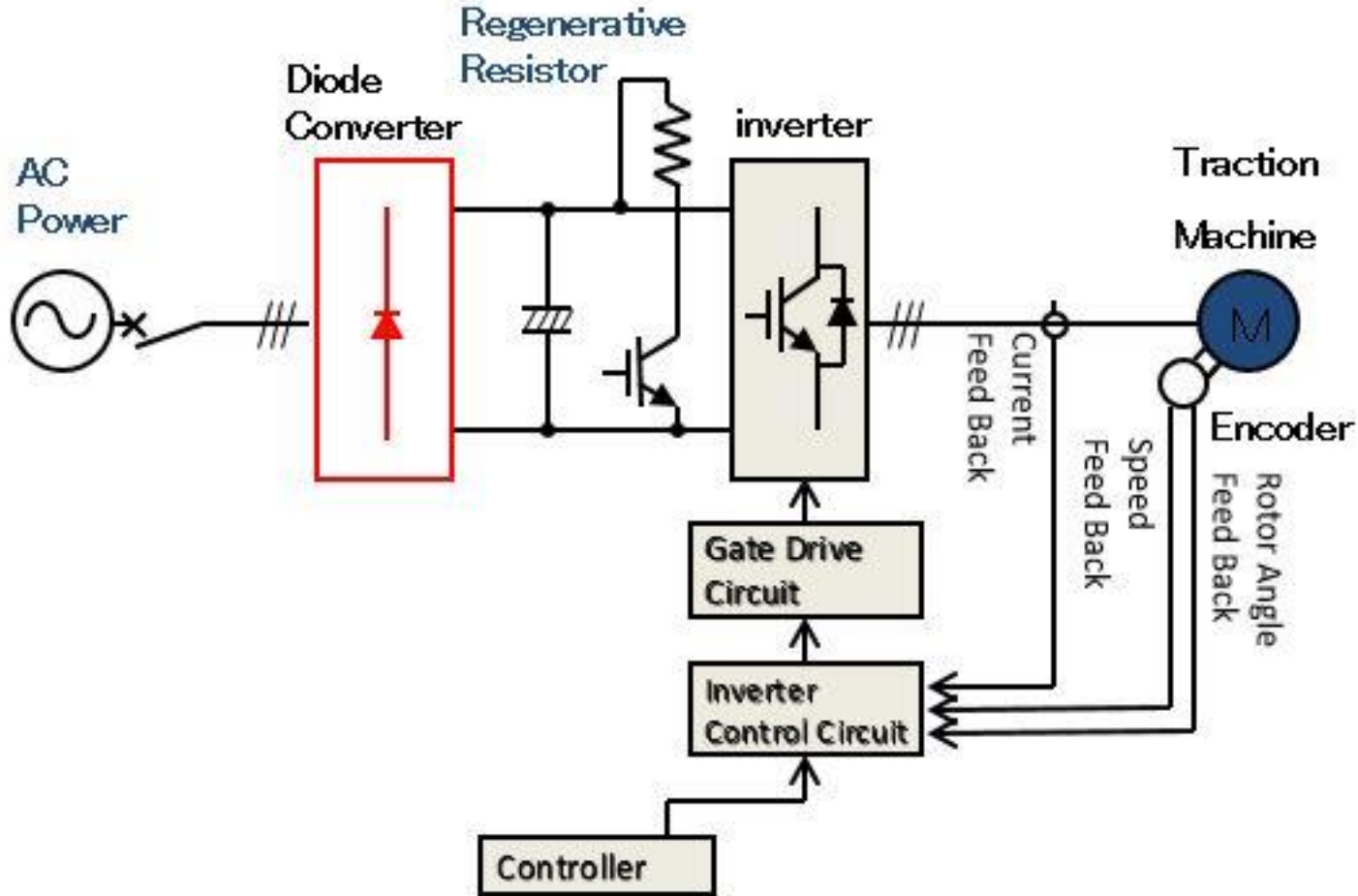


Regenerative Converter

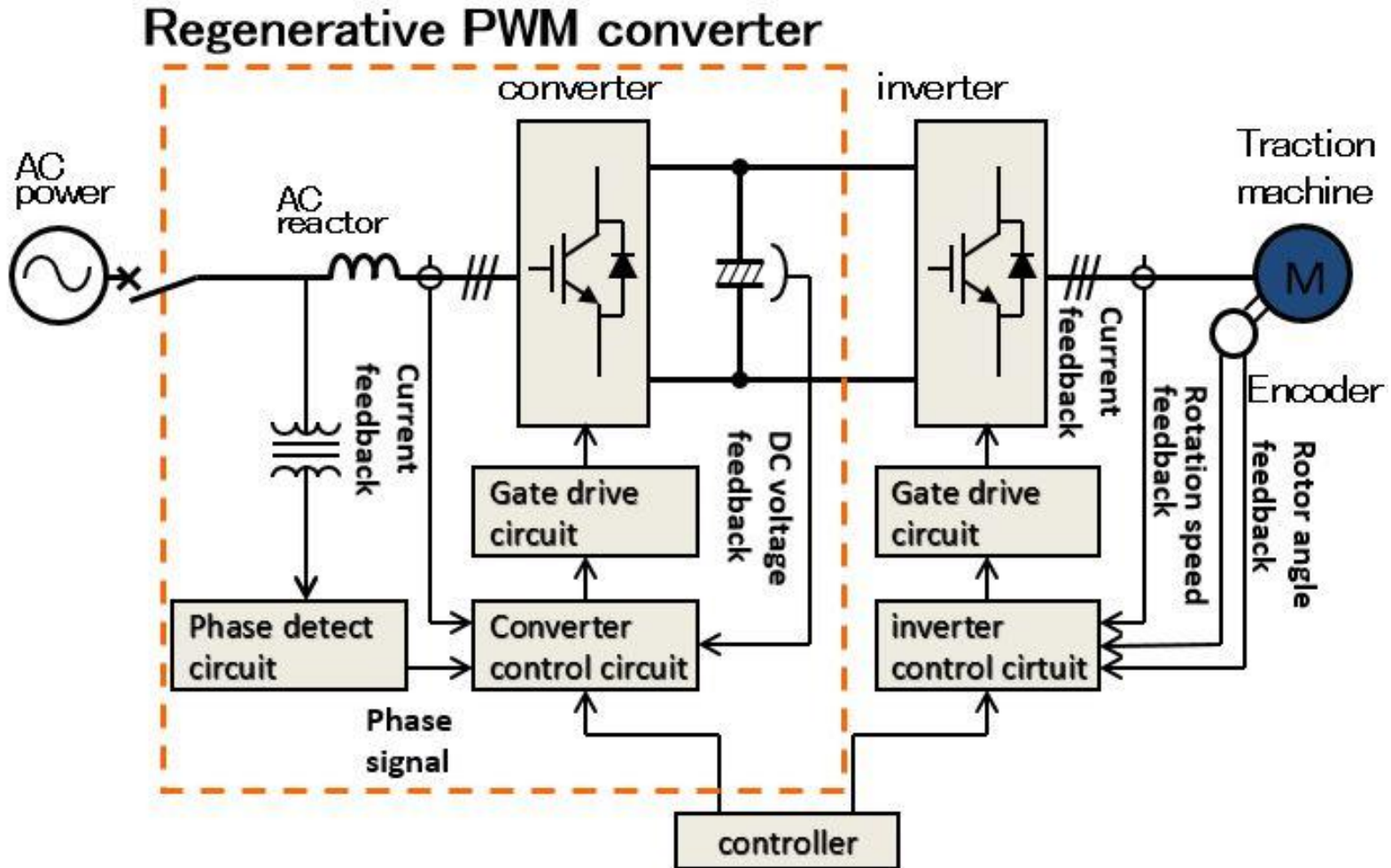


1. Elevator system design: cage weight + 50% rated capacity = weight of counterweight
2. Under full load condition, cage side is heavier than counterweight side, motor is **consuming energy when moving up** but **generating energy when moving down**
3. Under no load condition, cage side is lighter than counterweight side, motor is **consuming energy when moving down** but **generating energy when moving up**

Regenerative Converter



Regenerative Converter



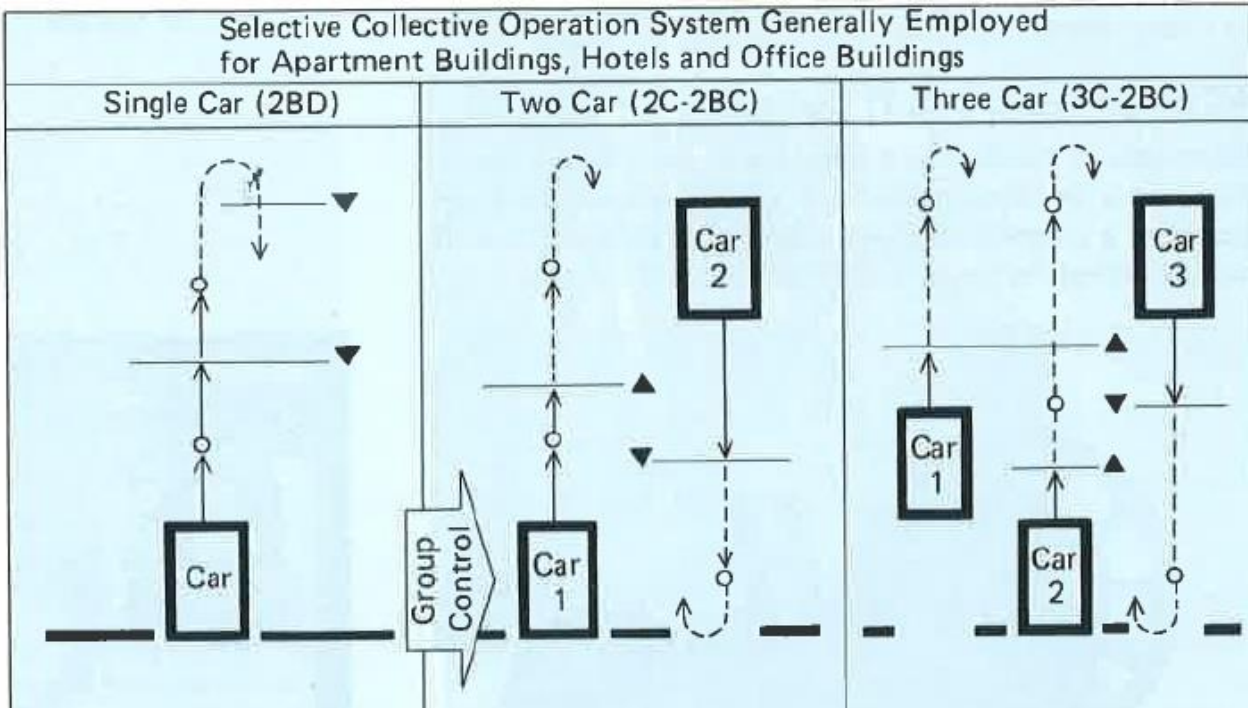
Regenerative Converter

Project	Commercial Building A	Commercial Building B	Residential Building C	Residential Building D
Capacity	1800kg	1600kg	750kg	900kg
Speed	8.0m/s	6.0m/s	3.0m/s	3.5m/s
% Regenerative Energy (24 hrs measurement)	45.8%	43.4%	21.6%	27.7%

Definition of Percentage of Regenerative Energy:

Total energy generated in regeneration mode/ Total energy consumed in motoring mode

2BC (2 Buttons selective Collective)

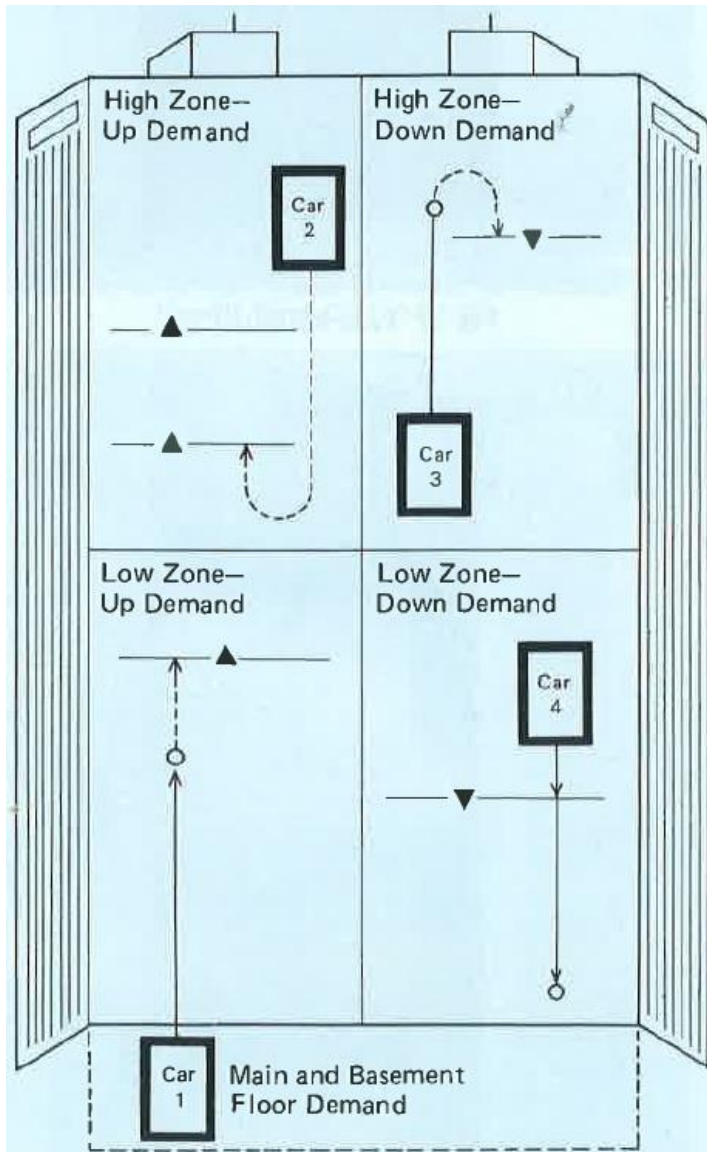


➤ Adopted in 1970's

➤ Highest Call Reversal

➤ Lowest Call Reversal

OS-75 (Optimum Service)

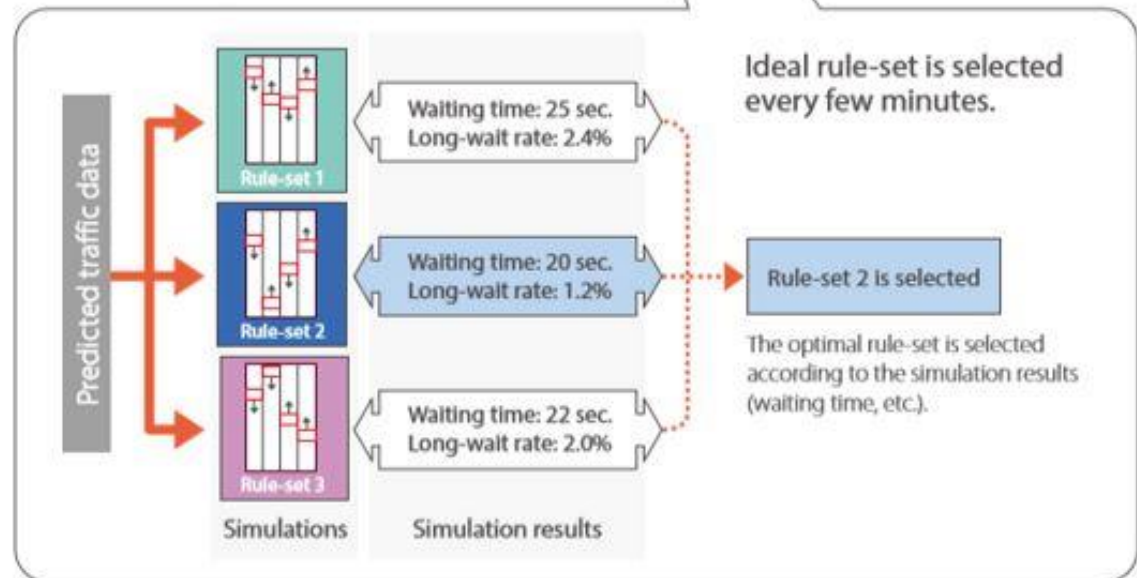
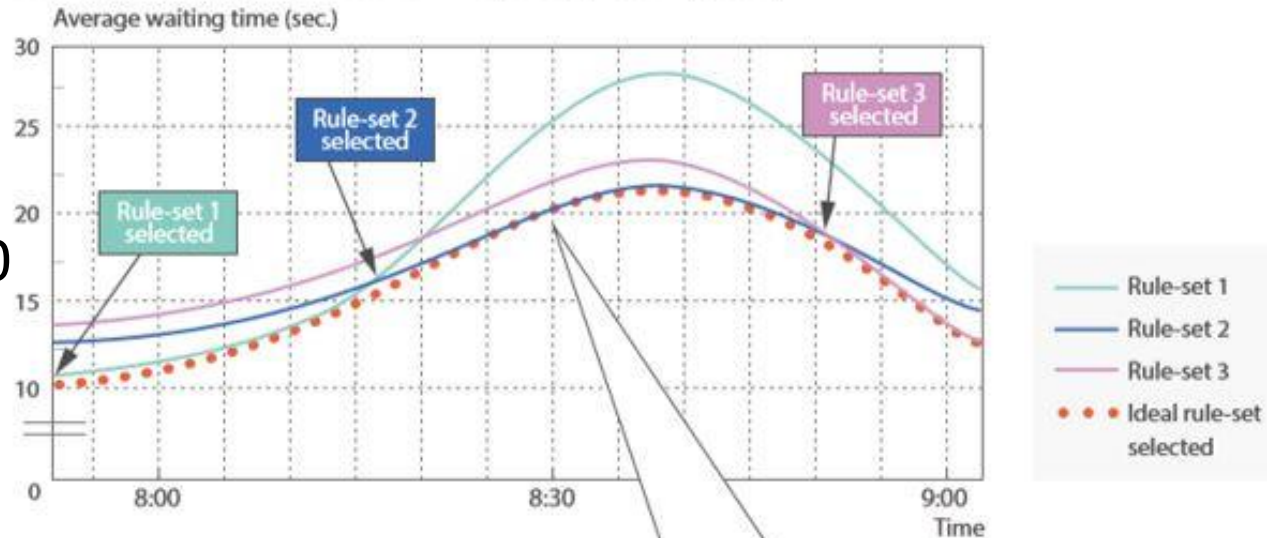


- Adopted in 1980's
- Demand Zones (in priority)
 - Main floor up demand
 - High zone down demand
 - Low zone up demand
 - Low zone down demand
 - High zone up demand
- Dynamic assignment of zones

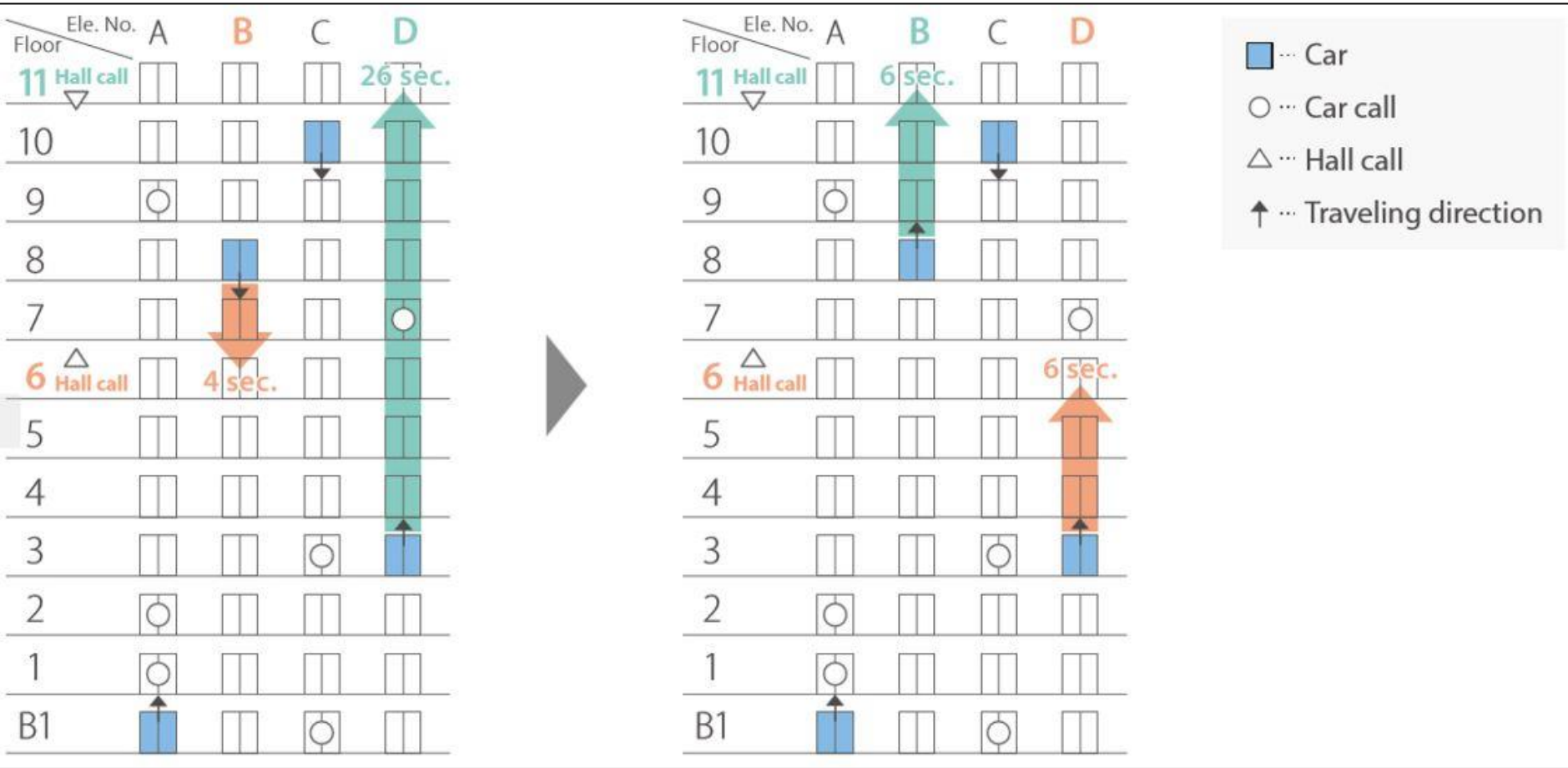
ΣAI-2200C

- Adopted in late 1990's and after 2000
- Traffic demand predication
- Rule-set simulator

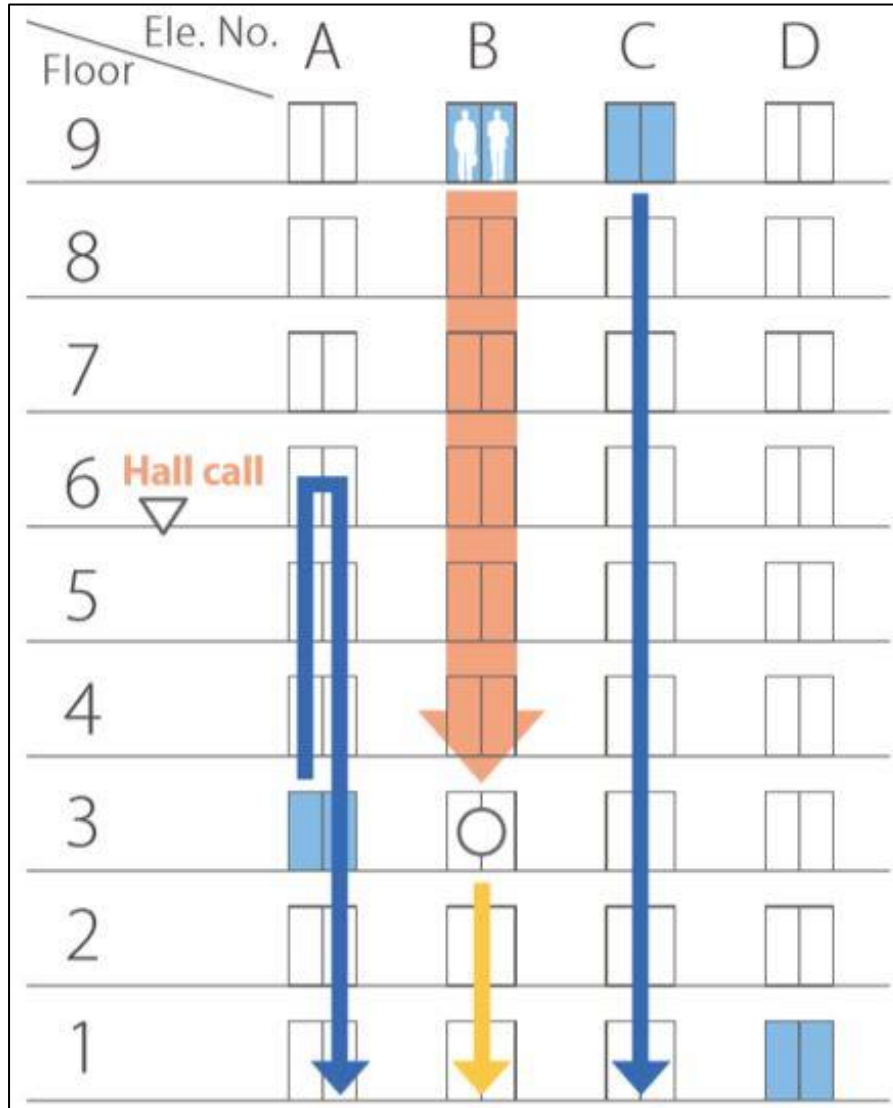
Performance results of each rule-set (average waiting time)



Cooperative Optimization Assignment



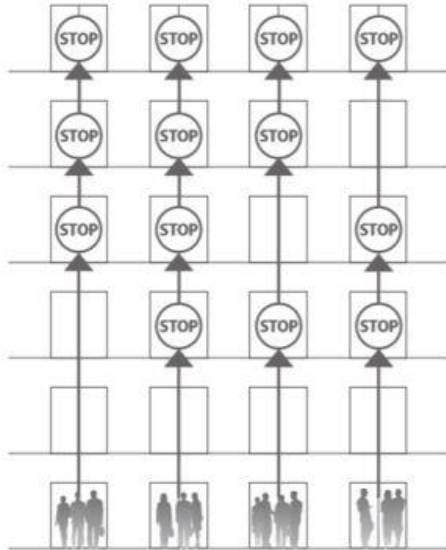
Energy Saving – Allocation Control



Destination Oriented Allocation System (DOAS)

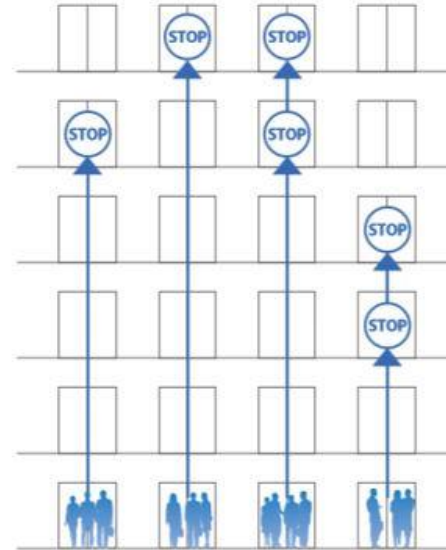
Without DOAS

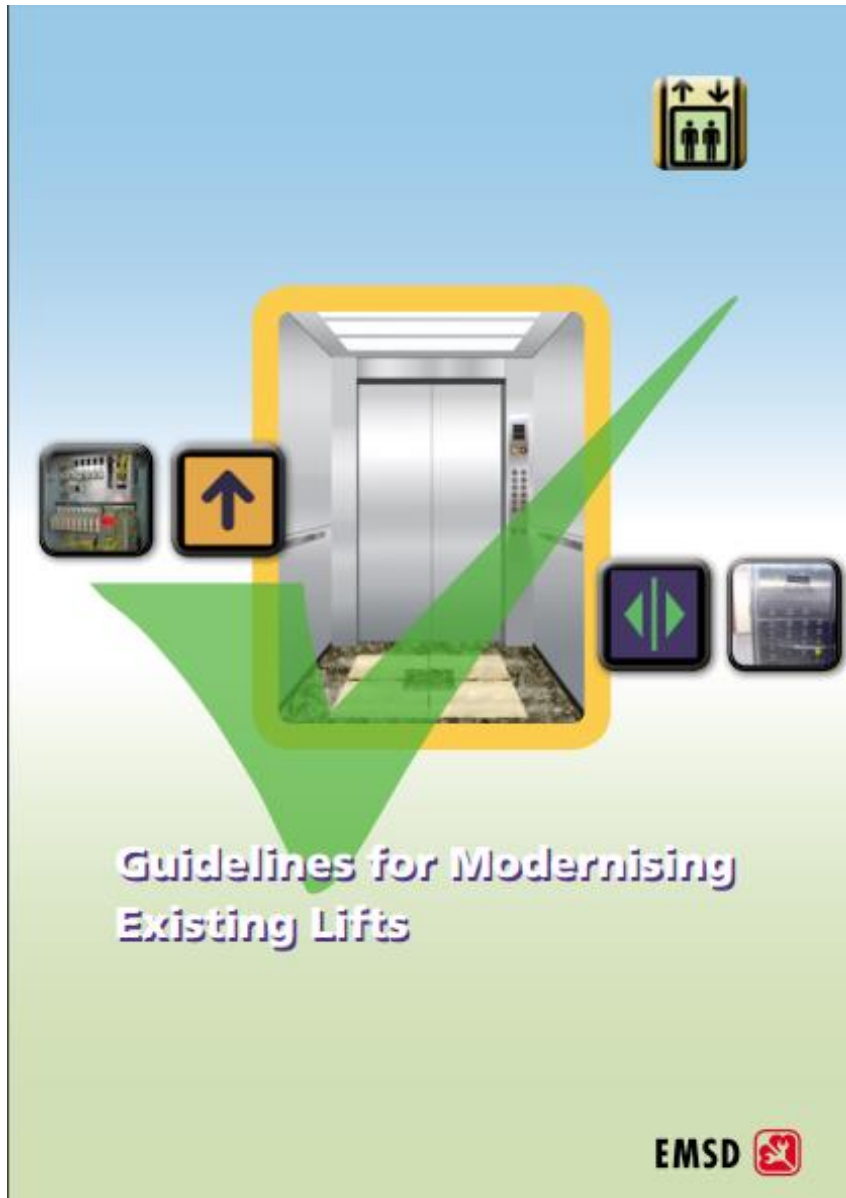
Cars make stops at every selected floor because destination floor is not considered for car allocation .




With DOAS

The individualized car allocation based on the destination floors leads to shorter travel time and fewer intermediate stops.

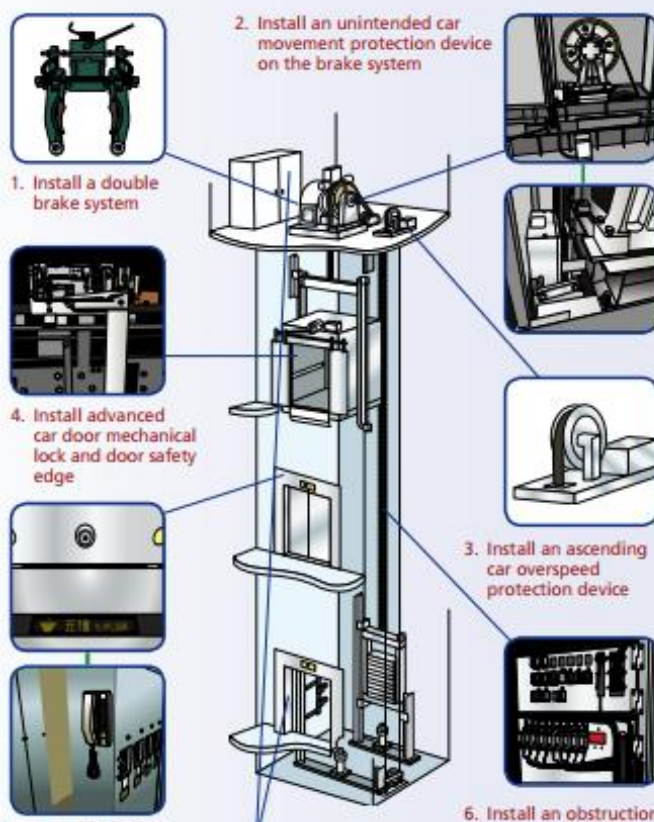




Guidelines for Modernising Existing Lifts

EMSD 

Applicable Solutions for Enhancing Requirements of Existing Lifts



1. Install a double brake system
2. Install an unintended car movement protection device on the brake system
3. Install an ascending car overspeed protection device
4. Install advanced car door mechanical lock and door safety edge
5. Add an intercom & CCTV system
6. Install an obstruction switch to protect suspension ropes
7. Add automatic rescue devices

5

Safety Codes

Frequency	Severity			
	I	II	III	IV
	Number of Hazardous Situation			
A				
B			30	
C		6, 25, <u>30</u> , 60	37, 46, 57	
C-D	70	3, 9, 15, 17, 19, 22, 23, 27, 40, 50, 56, 71	29, 45	
D	1, 3, 7, 8, 12, 13, 14, 16, 17, 26, 27, 31, 32, 33, 34, 39, 40, 43, 50, 53, 60	18, 21, 24, 41, 44, 47, 48, <u>52</u> , 63, 65	28, 42, 49, 61, <u>64</u>	
D-E	35, 36, 51, 52, 68, <u>72</u> , 74	20, 38, 55, 67, 69, 73		
E	10, 11, 24, 55, 73			
F				

Severity: I: Catastrophic II: Critical III: Marginal IV: Negligible

Frequency: A: Frequent B: Probable C: Occasional D: Remote E: Improbable F: Impossible

Priority

- Extreme
- High
- Medium
- Low

Conclusion



Thank you